

Effective Field Theory of Structure Formation

Lecture 3: Biased Tracers

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Tonale Winter School on Cosmology 2023

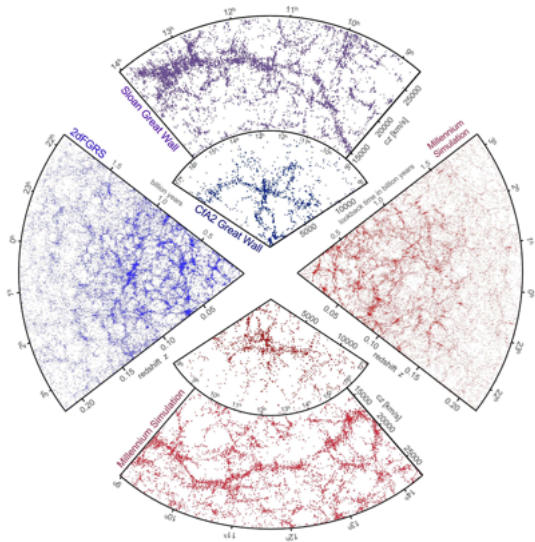
Outline:

1. Biased tracer in Eulerian picture
2. Non-locality in time and the equivalence of basis
3. Renormalization of bias coefficients
4. Bootstrap approach to galaxy bias
5. Biasing of shapes
6. Summary

Selected bibliography:

- Large-Scale Galaxy Bias, Desjacques et al., 2018, 1611.09787
- Lectures on EFTofLSS, Senatorel, (online notes)
- Modern Cosmology, Dodelson & Schmidt, 2021
- LSS of the Universe and PT, Bernardeau et al., 2002, astro-ph/0112551

Galaxies and galaxy halos



[Desjacques++:18]

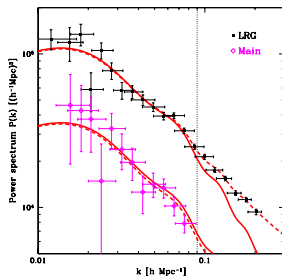
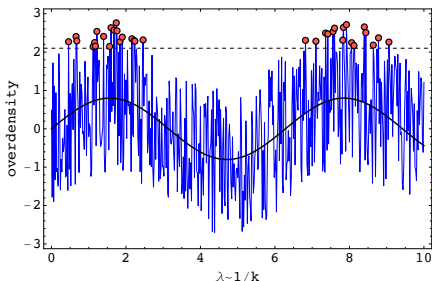
Galaxies and galaxy halos



Galaxies and their relation to dark matter distribution

Galaxies form at high density peaks of matter density:

rare peaks \implies higher clustering!



Tracer detracts the amplitude: $P_g(k) \sim b^2 P_m(k) + \dots$ on large scales.

Understanding **galaxy bias** is crucial for understanding the galaxy clustering.

Coefficients incorporate complicated **small scale (UV) physics**:

- dark matter halo formation & merger history
- chemistry and cooling processes & background radiation
- feedback processes (SN, AGN, ...)
- (and more ...)

Canonical approaches to galaxy biasing

Local biasing model: relation to dark matter

$$\delta_h = c_\delta \delta + c_{\delta^2} \delta^2 + c_{\delta^3} \delta^3 + \dots \quad [\text{Fry}+:93]$$

Quasi-local (in space): [McDonald+:09]

$$\begin{aligned} \delta_h(\mathbf{x}) = & c_\delta \delta(\mathbf{x}) + c_{\delta^2} \delta^2(\mathbf{x}) + c_{\delta^3} \delta^3(\mathbf{x}) \\ & + c_{s^2} s^2(\mathbf{x}) + c_{\delta s^2} \delta(\mathbf{x}) s^2(\mathbf{x}) + c_\epsilon \epsilon + \dots, \end{aligned}$$

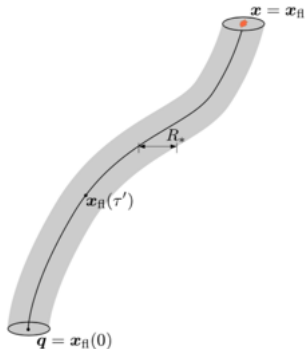
with effective (bias) coefficients c_l and operators:

$$s_{ij}(\mathbf{x}) = \partial_i \partial_j \phi(\mathbf{x}) - \frac{1}{3} \delta_{ij}^K \delta(\mathbf{x}), \dots \quad [\text{from Desjacques}++:18]$$

where ϕ is the gravitational potential, and white noise (stochasticity) ϵ .

Complete set set of operators including non-locality in time effects!

[Senatore:14, Angulo++:15, Desjacques++:18, ...]



Scalar field biasing: effective approach

[Desjacques++:18, ...]

Alternative systematisation in terms of derivatives of potential ϕ :

$$\Pi_{ij}^{[1]} = \frac{2}{3\Omega_m \mathcal{H}^2} k_i k_j \phi,$$

with higher operators O_h :

$$(1) \quad \text{tr}[\Pi^{[1]}],$$

$$(2) \quad \text{tr}[(\Pi^{[1]})^2], \quad \left(\text{tr}[\Pi^{[1]}]\right)^2,$$

$$(3) \quad \text{tr}[(\Pi^{[1]})^3], \quad \text{tr}[(\Pi^{[1]})^2] \text{tr}[\Pi^{[1]}], \quad \left(\text{tr}[\Pi^{[1]}]\right)^3, \quad \text{tr}[\Pi^{[1]}\Pi^{[2]}],$$

and additional derivative operators $R_*^2 \nabla^2 \text{tr}[\Pi^{[1]}], \dots$

- series allows one to estimate the higher order (theory) errors
- coefficients - physics from the R_* scale (some degeneracies)

Tracer field is then given

$$\delta_s(\mathbf{x}) = \sum_O b_O^{(s)} \text{tr}[O_{ij}](\mathbf{x}),$$

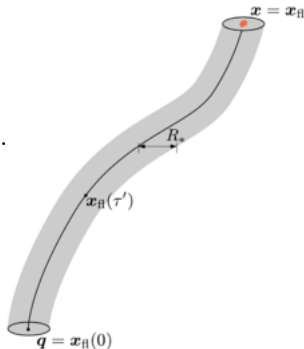
Effective field theory of biasing

Non-local (time) and quasi-local (space) relation of tracers to the dark matter [Senatore 2014, Mirbabayi et al, 2014]

$$\begin{aligned} \delta_h(\mathbf{x}, t) \simeq & \int^t dt' H(t') \left[\bar{c}_\delta(t, t') \delta(\mathbf{x}_H, t') \right. \\ & + \bar{c}_{\delta^2}(t, t') \delta(\mathbf{x}_H, t')^2 + \bar{c}_{s^2}(t, t') s^2(\mathbf{x}_H, t') + \dots \\ & \left. + \bar{c}_{\partial^2 \delta}(t, t') \frac{\partial^2_{\mathbf{x}_H}}{k_M^2} \delta(\mathbf{x}_H, t') + \dots \right] \end{aligned}$$

Fields evaluated on a past path:

$$\mathbf{x}_H(\mathbf{x}, \tau, \tau') = \mathbf{x} - \int_{\tau'}^{\tau} d\tau'' \mathbf{v}(\tau'', \mathbf{x}_H(\mathbf{x}, \tau, \tau''))$$



[from Desjacques++:18]

Alternative - all effects chaptered in Lagrangian approach.

Assembly bias effects captured in the scheme.

Effective field theory of biasing

New physical scale $k_M \sim 2\pi \left(\frac{4\pi}{3} \frac{\rho_0}{M}\right)^{1/3}$.

Can be different than k_{NL} . **Interesting case** $k_{NL} \gg k_M$!

We look at the correlations at $k \ll k_M$.

Each order in perturbation theory we get new bias coefficients:

$$\begin{aligned}\delta_h(k, t) &= \int_t \tilde{c}_{\delta,1} \left[D_t \delta^{(1)}(k) + \text{flow terms} \right] + \int_t \tilde{c}_{\delta,2} \left[D_t^2 \delta^{(2)}(k) + \text{flow terms} \right] + \dots \\ &= c_{\delta,1} \left[\delta^{(1)}(k) + \text{flow terms} \right] + c_{\delta,2} \left[\delta^{(2)}(k) + \text{flow terms} \right] + \dots\end{aligned}$$

Emergence of degeneracy: choice of most convenient basis

Renormalization! (takes care of short distance effects at long distances)

In practice, $\tilde{c}_{\delta,1}$ is a bare parameter, the sum of a finite part and a counterterm:

$$\tilde{c}_{\delta,1} = \tilde{c}_{\delta,1, \text{ finite}} + \tilde{c}_{\delta,1, \text{ counter}},$$

After renormalization we end up with using 7 finite bias parameters b_i .

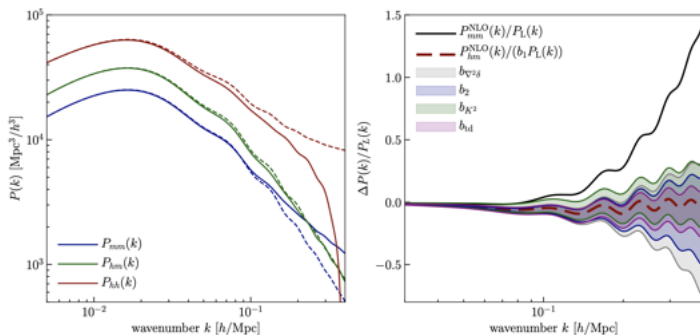
Observables: P_{hm} , P_{hh} , B_{hmm} , B_{hhm} , B_{hhh}

Power Spectrum

2-point observables:

$$P_{gm} = b_1 P_{mm} + b_{\delta^2} P_{\delta(2)\delta^2} + b_{s^2} P_{\delta(2)s^2} + (\text{3rd order}) - b_{\nabla^2} k^2 / k_M^2 P_L + (\text{noise}),$$
$$P_{gg} = b_1^2 P_{mm} + \sum_{O \in \{\delta^2, s^2\}} b_O b_{O'} P_{OO'} + (\text{3rd order}) - b_1 b'_{\nabla^2} k^2 / k_M^2 P_L + (\text{noise}).$$

We also now know how to add also the IR-resummation! (Long displacement)



[Desjacques++:18]

Adding baryonic effects

Baryons at large distances described as additional fluid component
(short distance physics is encoded in an effective stress tensor)

$$\delta_h(\mathbf{x}, t) = \int^t dt' H(t') \left[\bar{c}_{\partial^2 \phi}(t, t') \frac{\partial^2 \phi(\mathbf{x}_{\text{fl}}, t')}{H(t')^2} + \bar{c}_{\delta_b}(t, t') w_b \delta_b(\mathbf{x}_{\text{fl}, b}) \right. \\ \left. + \bar{c}_{\partial_i v_c^i}(t, t') w_c \frac{\partial_i v_c^i(\mathbf{x}_{\text{fl}, c}, t')}{H(t')} + \bar{c}_{\partial_i v_b^i}(t, t') w_b \frac{\partial_i v_b^i(\mathbf{x}_{\text{fl}, b}, t')}{H(t')} \right. \\ \left. \dots \right]$$

where ϕ is defined by Poisson equation and:

$$\mathbf{x}_{\text{fl}, b}(\mathbf{x}, \tau, \tau') = \mathbf{x} - \int_{\tau'}^{\tau} d\tau'' \mathbf{v}_b(\tau'', \mathbf{x}_{\text{fl}}(\mathbf{x}, \tau, \tau'')) , \\ \mathbf{x}_{\text{fl}, c}(\mathbf{x}, \tau, \tau') = \mathbf{x} - \int_{\tau'}^{\tau} d\tau'' \mathbf{v}_c(\tau'', \mathbf{x}_{\text{fl}}(\mathbf{x}, \tau, \tau''))$$

Similar expressions valid when including **neutrinos**, **clustering dark energy** ...

Adding Non-Gaussianities

For non-Gaussian fluctuations present only in the initial conditions and effect described by the squeezed limit, $k_L \ll k_S$ of correlations.

After horizon re-entry, but still early enough to neglect all gravitational non-linearities, the primordial density fluctuation are given by

$$\delta^{(1)}(\mathbf{k}_S, t_{\text{in}}) \simeq \delta_g(\mathbf{k}_S) + f_{\text{NL}} \tilde{\phi}(\mathbf{k}_L, t_{\text{in}}) \delta_g(\mathbf{k}_S - \mathbf{k}_L, t_{\text{in}}) ,$$

where $\tilde{\phi}(\mathbf{k}_L, t_{\text{in}}) \sim \frac{1}{k_S^2 T(k)} \left(\frac{k_L}{k_S}\right)^\alpha \delta_g(\mathbf{k}_L, t_{\text{in}})$ with a transfer function $T(k)$.

In the presence of primordial non-Gaussianities, additional components:

$$\begin{aligned} \delta_h(\mathbf{x}, t) &\simeq f_{\text{nl}} \tilde{\phi}(\mathbf{x}_{\text{H}}(t, t_{\text{in}}), t_{\text{in}}) \\ &\times \int^t dt' H(t') \left[\bar{c} \tilde{\phi}(t, t') + \bar{c}_{\partial^2 \phi} \tilde{\phi}(t, t') \frac{\partial^2 \phi(\mathbf{x}_{\text{H}}, t')}{H(t')^2} + \dots \right] \\ &+ f_{\text{nl}}^2 \tilde{\phi}(\mathbf{x}_{\text{H}}(t, t_{\text{in}}), t_{\text{in}})^2 \int^t dt' H(t') \left[+ \dots \right] \end{aligned}$$

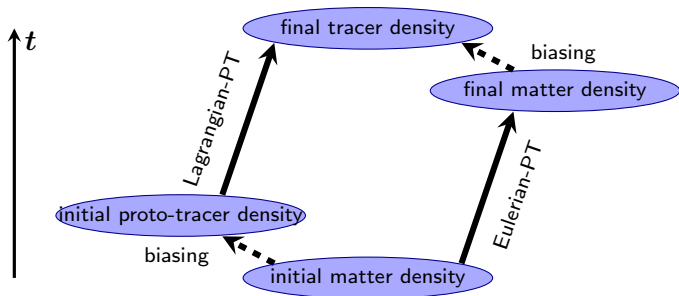
Non-linear dynamics and galaxy bias

- **Eulerian bias**: relates final d.m. density field and the final halo density

$$\delta_g(\mathbf{x}) = c_{\delta}^e \delta(\mathbf{x}) + c_{\delta^2}^e \delta^2(\mathbf{x}) + c_{s^2}^e s^2(\mathbf{x}) + \dots + c_{\partial^2 \delta}^e \frac{\partial^2}{k_*^2} \delta(\mathbf{x}) + \text{“stochastic”} + \dots$$

- **Lagrangian bias**: relates initial d.m. density field and the proto-halo density

$$\delta_g(\mathbf{q}) = c_{\delta}^l \delta_L(\mathbf{q}) + c_{\delta^2}^l \delta_L^2(\mathbf{q}) + c_{s^2}^l s_L^2(\mathbf{q}) + \dots + c_{\partial^2 \delta}^l \frac{\partial^2}{k_*^2} \delta_L(\mathbf{q}) + \text{“stochastic”} + \dots,$$

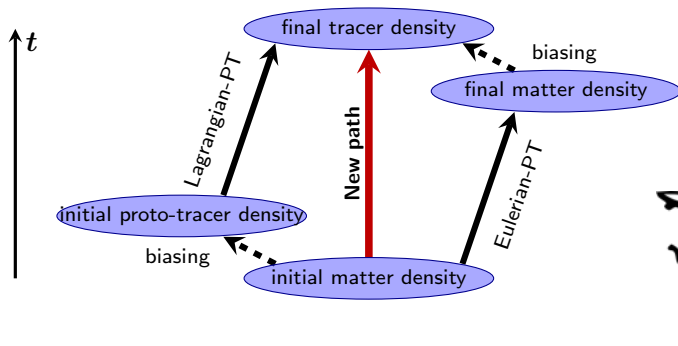


A new look at bias expansion: “Bootstrap in LSS”

A new idea:

[Fujita+:2020]

- (I.) construct a bias of operators from linear density - as a Monkey would,
- (II.) impose physical constraints - consistency relations in LSS



A similar approach also done in [D'Amico++:2021] .

A new look at bias expansion: “Bootstrap in LSS”

A new idea:

- (I.) construct a bias of operators from linear density - as a Monkey would,
- (II.) impose physical constraints - consistency relations in LSS

How do we describe the system for a tracer?

Balance equations:

$$\begin{aligned}\partial_\tau \delta_\alpha(\mathbf{x}) + \nabla \cdot ([1 + \delta_\alpha] \mathbf{u}_\alpha)(\mathbf{x}) &= S_\delta[\delta](\mathbf{x}), \\ \partial_\tau \mathbf{u}_\alpha(\mathbf{x}) + \mathcal{H} \mathbf{u}_\alpha(\mathbf{x}, \tau) + \mathbf{u}_\alpha(\mathbf{x}, \tau) \cdot \nabla \mathbf{u}_h(\mathbf{x}, \tau) &= -\nabla \phi(\mathbf{x}, \tau) + S_u[\delta](\mathbf{x}),\end{aligned}$$

The lhs. terms are:

$$\nabla^2 \phi(\mathbf{x}) \propto \delta_m(\mathbf{x}),$$

and small scale sources $S_\delta(\mathbf{x})$, $S_u(\mathbf{x})$ typically suppressed by some scale k_* .

The key notion is the separation of scales in the system, i.e. gravity dominates on large scales.

I. Specifying the non-linear terms

This is the “Monkey part”:

$$\text{Continuity eq. : } \partial_\tau \delta + (\text{linear terms}) = -\delta\theta - \partial_i \delta \frac{\partial_i}{\partial^2} \theta,$$

$$\text{Euler eq. : } \partial_\tau \theta + (\text{linear terms}) = -\frac{\partial_i \partial_j}{\partial^2} \theta \frac{\partial_i \partial_j}{\partial^2} \theta,$$

where δ is the density and θ is the velocity divergence.

Solution is constructed by the iterative “Monkey” process

$$\left\{ XY, \quad \partial_i X \frac{\partial_i}{\partial^2} Y, \quad \frac{\partial_i \partial_j}{\partial^2} X \frac{\partial_i \partial_j}{\partial^2} Y \right\},$$

where X and Y are drawn from the list of the lower order operators.

New bias basis:

$$\begin{aligned} \delta_\alpha = & a_1 \delta_L \\ & + b_1 \delta_L^2 + b_2 \partial_i \delta_L \frac{\partial_i}{\partial^2} \delta_L + b_3 \frac{\partial_i \partial_j}{\partial^2} \delta_L \frac{\partial_i \partial_j}{\partial^2} \delta_L + \dots \end{aligned}$$



In the paper we keep terms up to the third order terms in PT.

II. Constraining the coefficients

Consistency relations of LSS are direct consequence of the **equivalence principle** and **adiabatic initial conditions**:

$$\langle \delta_{\mathbf{k}}^m(\tau) \delta_{\mathbf{q}_1}^g(\tau_1) \dots \delta_{\mathbf{q}_n}^g(\tau_n) \rangle' \sim -P_g(\mathbf{k}, \tau) \sum_{\alpha} \frac{D(\eta_{\alpha})}{D(\eta)} \frac{\mathbf{k} \cdot \mathbf{q}_{\alpha}}{k^2} \langle \delta_{\mathbf{q}_1}^g(\eta_1) \dots \delta_{\mathbf{q}_n}^g(\eta_n) \rangle', \quad \text{as } k \rightarrow 0.$$

Tree-level statistics is the simplest way to impose the constraints:

$$\lim_{k \rightarrow 0} \langle \delta_{\mathbf{k}} \delta_{\mathbf{q}_1}^{\alpha} \delta_{\mathbf{q}_2}^{\beta} \rangle' = \left(a_1^{(\alpha)} b_2^{(\beta)} - a_1^{(\beta)} b_2^{(\alpha)} \right) \frac{\mathbf{k} \cdot \mathbf{q}_1}{2k^2} P_{\ell}(k) P_{\ell}(q_1) + \mathcal{O}(k^0),$$

By requiring the IR-divergent term to vanish we get:

$$\frac{b_2^{(\alpha)}}{a_1^{(\alpha)}} = \frac{b_2^{(\beta)}}{a_1^{(\beta)}} = \mathcal{C}(\tau).$$

The $\mathcal{C}(\tau)$ is universal, **tracers independent**, function of time.

Fixing the dynamical degrees of freedom

New bias expansion:

$$\delta_g = a_1 \left[\delta_L + \mathcal{C} \partial_i \delta_L \frac{\partial_i}{\partial^2} \delta_L \right] + b_1 \delta_L^2 + b_3 \left(\frac{\partial_i \partial_j}{\partial^2} \delta_L \frac{\partial_i \partial_j}{\partial^2} \delta_L \right) + (\text{3rd order})$$

How to determine the **universal coefficients** $\mathcal{C}(\tau)$?

Easy way is to fix it to the simple **'tracer' of dark matter**: dark matter!

$$\mathcal{C} = 1.$$

In general these coefficients reflect dynamics and modifications of GR!

Example: clustering quintessence

$$\mathcal{C} = 1 - \epsilon(\tau),$$

where ϵ depends on the quintessence field and τ .

This motivates the construction on the near-optimal estimators for \mathcal{C} .

Ellipsoids, 2-tensors, galaxy shapes

How can we describe the field of ellipsoids?

Ellipsoid – 3 parameters;

$$T_{ij}^0 = \begin{pmatrix} 1/a^2 & 0 & 0 \\ 0 & 1/b^2 & 0 \\ 0 & 0 & 1/c^2 \end{pmatrix}$$

Rotation matrix – 3 Euler angles;

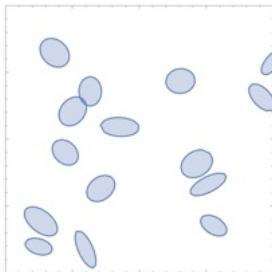
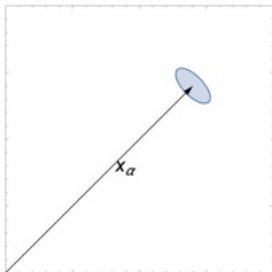
$$\mathcal{R}_{ij}(\psi, \theta, \phi) \implies \mathbf{T} = \mathcal{R}\mathbf{T}^0\mathcal{R}^T$$

Ellipsoid equation;

$$(\mathbf{x} - \mathbf{x}_\alpha) \cdot \mathbf{T}^{(\alpha)} \cdot (\mathbf{x} - \mathbf{x}_\alpha) = 1$$

Tensor field:

$$T_{ij}(\mathbf{x}) = \sum_{\alpha} T_{ij}^{(\alpha)}(\mathbf{x}_\alpha) \delta^D(\mathbf{x} - \mathbf{x}_\alpha)$$



Biasing of shapes in 3D: effective approach

Expansion of the field of galaxy shapes:

$$g_{ij}(\mathbf{x}) = \sum_{\mathcal{O}} b_{\mathcal{O}}^{(g)} \text{TF}[O_{ij}](\mathbf{x}).$$

where the list of operators (up to higher derivatives and stochastic contributions) is

- (1) $\text{TF}[\Pi^{[1]}]_{ij}$, [Hirata&Seljak : 04]
- (2) $\text{TF}[\Pi^{[2]}]_{ij}$, $\text{TF}[(\Pi^{[1]})^2]_{ij}$, $\text{TF}[\Pi^{[1]}]_{ij} \text{tr}[\Pi^{[1]}]$,
- (3) $\text{TF}[\Pi^{[3]}]_{ij}$, $\text{TF}[\Pi^{[1]}\Pi^{[2]}]_{ij}$, $\text{TF}[\Pi^{[2]}]_{ij} \text{tr}[\Pi^{[1]}]$,
 $\text{TF}[(\Pi^{[1]})^3]_{ij}$, $\text{TF}[(\Pi^{[1]})^2]_{ij} \text{tr}[\Pi^{[1]}]$, $\text{TF}[\Pi^{[1]}]_{ij} (\text{tr}[\Pi^{[1]}])^2 \dots$

Derivative operators relevant for leading power spectrum corrections

$$R_*^2 \nabla^2 \text{TF}[\Pi^{[1]}]_{ij}.$$

Tensor fields and galaxy intrinsic alignments

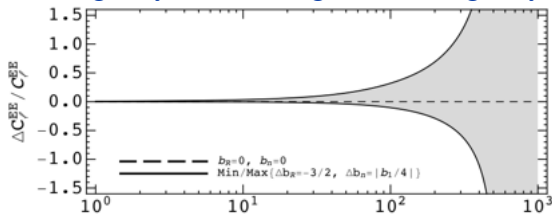
Expansion of the field of galaxy shapes:

$$g_{ij}(\mathbf{x}) = \sum_O c_o O_{ij}(\mathbf{x}),$$

with biasing operator basis

- (1) TF $[\Pi^{[1]}]_{ij}$,
- (2) TF $[\Pi^{[2]}]_{ij}$, TF $[(\Pi^{[1]})^2]_{ij}$, TF $[\Pi^{[1]}]_{ij} \text{tr}[\Pi^{[1]}]$

Relevant for: galaxy intrinsic alignment and galaxy lensing.



Formalism can be used as a probe of cosmological collider physics.